

## VZORCE

$$u = Ri, \quad i = \frac{u}{R}, \quad R = \frac{u}{i},$$

$$q = Cu, \quad u = \frac{q}{C}, \quad C = \frac{q}{u},$$

$$q(t) = I.t, \quad \text{take } u(t) = \frac{I.t}{C}.$$

$$q(T) = \int_{t_0}^T i(t)dt + q(t_0), \quad \text{take } u(T) = \frac{1}{C} \int_{t_0}^T i(t)dt + \frac{q(t_0)}{C}.$$

$$i(t) = C \frac{du(t)}{dt}$$

$$\Phi = L.i, \quad i = \frac{\Phi}{L}, \quad L = \frac{\Phi}{i}.$$

$$u(t) = \frac{d\Phi(t)}{dt}, \quad \text{take } u(t) = L \frac{di(t)}{dt}.$$

$$i(T) = \frac{1}{L} \int_{t_0}^T u(t)dt + i(t_0).$$

$$i(t) = \frac{U}{L}t, \quad i(T) = \frac{U.T}{L}.$$

$$P(t) = u(t) \cdot i(t).$$

$$W(T) = \int_0^T P(t)dt = \int_0^T u(t)i(t)dt,$$

$$W_C = \frac{1}{2}C.U^2$$

$$W_L = \frac{1}{2}L.I^2,$$

$$u(t) = U_m \sin(\omega t)$$

$$U_{ef}^2 = \frac{1}{2\pi} \int_0^{2\pi} [U_m \sin(\omega t)]^2 dt$$

$$U_{ef} = \frac{1}{\sqrt{2}}U_m \quad \rightarrow \quad U_{ef} \approx 0,707U_m$$

$$\sum_{n=1}^N i_n(t) = 0.$$

$$\sum_1^n u_n(t) = 0.$$

$$u_z = u_0 \frac{R_z}{R_0 + R_z}.$$

$$\hat{\mathbf{U}} = \operatorname{Re}(\hat{\mathbf{U}}) + j \operatorname{Im}(\hat{\mathbf{U}}) = U_m (\cos \varphi + j \sin \varphi) = U_m e^{j\varphi}$$

$$\hat{\mathbf{I}} = \operatorname{Re}(\hat{\mathbf{I}}) + j \operatorname{Im}(\hat{\mathbf{I}}) = I_m (\cos \varphi + j \sin \varphi) = I_m e^{j\varphi}$$

$$U_m = |\hat{\mathbf{U}}|, \quad \varphi = \operatorname{arctg} \frac{\operatorname{Im} \hat{\mathbf{U}}}{\operatorname{Re} \hat{\mathbf{U}}}$$

$$\hat{\mathbf{Y}}_2 = \hat{\mathbf{H}} \hat{\mathbf{Y}}_1,$$

$$y_1(t) = Y_{1m} \sin(\omega t + \varphi_1) \quad \text{a} \quad y_2(t) = Y_{2m} \sin(\omega t + \varphi_2),$$

$$Y_{2m} = Y_{1m} |\hat{\mathbf{H}}| = Y_{1m} \sqrt{(\operatorname{Re}(\hat{\mathbf{H}}))^2 + (\operatorname{Im}(\hat{\mathbf{H}}))^2}$$

$$\varphi_2 = \varphi_1 + \operatorname{arctg} \left( \frac{\operatorname{Im}(\hat{\mathbf{H}})}{\operatorname{Re}(\hat{\mathbf{H}})} \right).$$

$$f = \frac{1}{2\pi\sqrt{LC}}$$

$$i(t) = \frac{U}{R} e^{(-t/\tau)}$$

$$T = \tau \ln \frac{U_\infty - U_a}{U_\infty - U_b}$$